

# SGM42507 1.5A, 7.5V H-Bridge Driver for Motor/Coil

## **GENERAL DESCRIPTION**

The SGM42507 is an H-bridge driver designed for actuating motors and coils bi-directionally turning. It translates logic level input to power driving outputs to motors or coils, for different spinning or moving directions by PH-EN/FAULT interface. Internal overcurrent (OC) and under-voltage (UV) protection circuits, together with over-temperature (OT) circuit prevent the device from being in over-stress condition, while an alert output simplifies stalling sensing, which is a useful feature for most applications.

The SGM42507A is available in a Green TSOT-23-6 package. The SGM42507B/C are available in both Green SC70-6 and TSOT-23-6 packages. They operate over an ambient temperature range of -40°C to  $+125^{\circ}$ C.

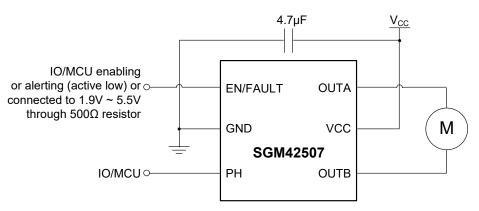
## FEATURES

- Compact Size and Smart Protection
- Support Fast Decay and Slow Decay Modes
- Internal OC/UV/OT Protections
  - Over-Current Threshold Options: 0.45A/0.9A/1.5A
  - Under-Voltage Protection Threshold Options: 1.75V/2.8V/3.6V
- Up to 7.5V Supply Range for Applications Powered by:
  - 1 Li+/Poly Cell
  - 2/3/4 Dry Cells
  - + 1/2 LiSOCI2 Cell(s)
- -40°C to +125°C Operating Temperature Range
- SGM42507A is Available in a Green TSOT-23-6 Package SGM42507B/C are Available in both Green SC70-6 and TSOT-23-6 Packages

## **APPLICATIONS**

Utility Meters, Robots, Solenoid

# TYPICAL APPLICATION





## **PACKAGE/ORDERING INFORMATION**

MODEL	PACKAGE DESCRIPTION	SPECIFIED TEMPERATURE RANGE	ORDERING NUMBER	PACKAGE MARKING	PACKING OPTION
SGM42507A-1.75	TSOT-23-6	-40°C to +125°C	SGM42507A-1.75XTN6G/TR	GM5XX	Tape and Reel, 3000
SGM42507A-2.8	TSOT-23-6	-40°C to +125°C	SGM42507A-2.8XTN6G/TR	GS0XX	Tape and Reel, 3000
SGM42507A-3.6	TSOT-23-6	-40°C to +125°C	SGM42507A-3.6XTN6G/TR	GS1XX	Tape and Reel, 3000
SGM42507B-1.75	SC70-6	-40°C to +125°C	SGM42507B-1.75XC6G/TR	GPBXX	Tape and Reel, 3000
3GW42307D-1.73	TSOT-23-6	-40°C to +125°C	SGM42507B-1.75XTN6G/TR	M09XX	Tape and Reel, 3000
SGM42507B-2.8	SC70-6	-40°C to +125°C	SGM42507B-2.8XC6G/TR	GW8XX	Tape and Reel, 3000
SGIVI42507B-2.0	TSOT-23-6	-40°C to +125°C	SGM42507B-2.8XTN6G/TR	MOAXX	Tape and Reel, 3000
SGM42507B-3.6	SC70-6	-40°C to +125°C	SGM42507B-3.6XC6G/TR	GW9XX	Tape and Reel, 3000
3GIM42307B-3.0	TSOT-23-6	-40°C to +125°C	SGM42507B-3.6XTN6G/TR	MOBXX	Tape and Reel, 3000
SGM42507C-1.75	SC70-6	-40°C to +125°C	SGM42507C-1.75XC6G/TR	GWAXX	Tape and Reel, 3000
36101423070-1.73	TSOT-23-6	-40°C to +125°C	SGM42507C-1.75XTN6G/TR	MOCXX	Tape and Reel, 3000
SCM42507C 2.9	SC70-6	-40°C to +125°C	SGM42507C-2.8XC6G/TR	GWBXX	Tape and Reel, 3000
SGM42507C-2.8	TSOT-23-6	-40°C to +125°C	SGM42507C-2.8XTN6G/TR	MODXX	Tape and Reel, 3000
SCM42507C 2 6	SC70-6	-40°C to +125°C	SGM42507C-3.6XC6G/TR	GWCXX	Tape and Reel, 3000
SGM42507C-3.6	TSOT-23-6	-40°C to +125°C	SGM42507C-3.6XTN6G/TR	MOEXX	Tape and Reel, 3000

## MARKING INFORMATION

NOTE: XX = Date Code.



Date Code - Month
Date Code - Year
Serial Number

Green (RoHS & HSF): SG Micro Corp defines "Green" to mean Pb-Free (RoHS compatible) and free of halogen substances. If you have additional comments or questions, please contact your SGMICRO representative directly.

## SELECTABLE MODEL

MODEL	OVER-CURRENT PROTECTION THRESHOLD (A)	UNDER-VOLTAGE PROTECTION THRESHOLD (V)
SGM42507A-1.75	1.5	1.75
SGM42507A-2.8	1.5	2.8
SGM42507A-3.6	1.5	3.6
SGM42507B-1.75	0.9	1.75
SGM42507B-2.8	0.9	2.8
SGM42507B-3.6	0.9	3.6
SGM42507C-1.75	0.45	1.75
SGM42507C-2.8	0.45	2.8
SGM42507C-3.6	0.45	3.6



## **ABSOLUTE MAXIMUM RATINGS**

V <sub>CC</sub>	0.3V to 9V <sup>(1)</sup>
Digital Input Pin Voltage Range	0.3V to 6V
Package Thermal Resistance	
SC70-6, θ <sub>JA</sub>	245.8°C/W
TSOT-23-6, θ <sub>JA</sub>	217.8°C/W
Junction Temperature	+150°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (Soldering, 10s)	+260°C
ESD Susceptibility	
HBM	5000V
MM	
CDM	1000V
NOTE 1: Guaranteed SGM42507 work	at 7.5V DC and surge
to 9V.	

## **RECOMMENDED OPERATING CONDITIONS**

V <sub>CC</sub>	1.9V to 7.5V
Digital Input Pin Voltage Range	0V to 5.5V
Operating Temperature Range	40°C to +125°C

## **OVERSTRESS CAUTION**

Stresses beyond those listed in Absolute Maximum Ratings may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect reliability. Functional operation of the device at any conditions beyond those indicated in the Recommended Operating Conditions section is not implied.

## **ESD SENSITIVITY CAUTION**

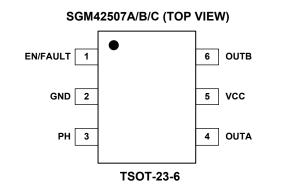
This integrated circuit can be damaged by ESD if you don't pay attention to ESD protection. SGMICRO recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage. ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

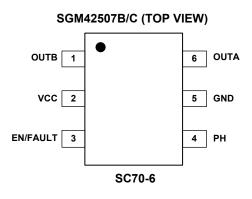
### DISCLAIMER

SG Micro Corp reserves the right to make any change in circuit design, or specifications without prior notice.



## **PIN CONFIGURATIONS**





## **PIN DESCRIPTIONS**

NAME	TYPE	FUNCTION
EN/FAULT	I/O	Enable Input or Alert Output (OTP, OCP, UVP). Logic high to enable normal operation, logic low (> t <sub>SLEEP</sub> ) to enter low power dissipation sleep mode and reset all internal logic. Internal pull-down. This output is not valid when the device into minimum power dissipation sleep mode.
GND	G	Ground.
PH	I	Direction Input ( $V_{PH} \le V_{CC}$ ). Logic high for sourcing from OUTA and sinking into OUTB; logic low for reverse driving. Internal pull-down.
OUTA	0	Output A of H-Bridge Driving Stage.
VCC	Р	Power Input. A 4.7µF (MIN) ceramic bypass capacitor to GND is recommended.
OUTB	0	Output B of H-Bridge Driving Stage.

NOTE: I: Input, O: Output, I/O: Input or Output, G: Ground, P: Power for the circuit.



# FUNCTIONAL BLOCK DIAGRAM

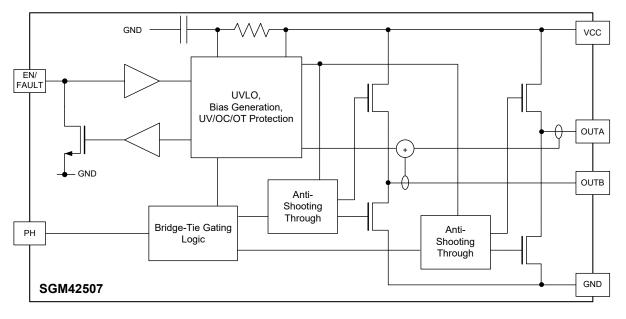
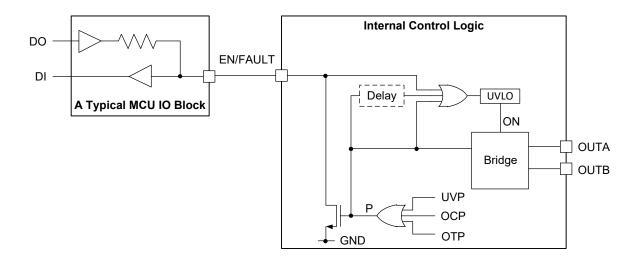


Figure 1. Block Diagram

# INTERNAL CONTROL LOGIC





## **ELECTRICAL CHARACTERISTICS**

 $(T_A = +25^{\circ}C, V_{CC} = 5V, EN/FAULT pin connected to 5V through 500\Omega$  resistor, Full = -40°C to +125°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
POWER SUPPLIES		1					
VCC Operating Supply Voltage	V <sub>cc</sub>		+25°C	1.9		7.5	V
Digital Input Voltage Range (EN/FAULT, PH)	V <sub>IN</sub>		+25°C	0		5.5	V
VCC Operating Supply Current	Ivcc	No PWM	+25°C		45	74	μA
VCC Sleep Mode Supply Current	Ivccq	EN/FAULT = GND	+25°C		1.3	2	μA
		SGM42507A/B/C-1.75	+25°C		1.7	1.9	
VCC Under-Voltage Lockout Voltage	V <sub>UVLO</sub>	SGM42507A/B/C-2.8	+25°C		1.95	2.15	V
		SGM42507A/B/C-3.6	+25°C		1.7	1.85	
VCC Under-Voltage Lockout Voltage Hysteresis	V <sub>HYS</sub>		+25°C		100		mV
		SGM42507A/B/C-1.75	+25°C		1.75	1.9	
VCC Under-Voltage Protection Voltage	VUVP	SGM42507A/B/C-2.8	+25°C		2.8	3.05	V
		SGM42507A/B/C-3.6	+25°C		3.6	3.75	
VCC Under-Voltage Protection Voltage Hysteresis	V <sub>HYS</sub>		+25°C		100		mV
LOGIC LEVEL INPUTS		·			•		•
Input Low Voltage	VIL		Full			0.6	V
Input High Voltage	V <sub>IH</sub>		Full	1.6			V
Input Low Current	IIL	V <sub>IN</sub> = 0V	+25°C	-500		500	nA
Input High Weak Pull-Down Current	I <sub>IH_weak</sub>	V <sub>IN</sub> = 5.5V	+25°C		60	85	μA
Input High Strong Pull-Down Current	I <sub>IH_strong</sub>	V <sub>IN</sub> = 1.1V	+25°C		300	380	μA
Input Deglitch Time	t <sub>DEG</sub>		+25°C		300		ns
EN/FAULT OUTPUT (OPEN-DRAIN OUTPUT	)						
Output Low Voltage	V <sub>OL</sub>	V <sub>CC</sub> = 1.8V, I <sub>OUT</sub> = -5mA	+25°C			170	mV
Output High Leakage Current	I <sub>OH</sub>		+25°C			95	μA
H-BRIDGE FETS							
		SCM425074 X L = 200m4	+25°C		375		
		SGM42507A-X, I <sub>OUT</sub> = 200mA	Full			550	
HS FET On-Resistance	P	SGM42507B-X, I <sub>OUT</sub> = 200mA	+25°C		385		- mΩ
no rei Oli-Resistance	$R_{DS(ON)}$	3910142307 B-X, 1 <sub>0UT</sub> - 20011A	Full			570	
		SCM42507C X I = 200mA	+25°C		400		
		SGM42507C-X, I <sub>OUT</sub> = 200mA	Full			600	
		SGM42507A-X, I <sub>OUT</sub> = -200mA	+25°C		180		
			Full			335	
LS FET On-Resistance	R <sub>DS(ON)</sub> SGM42507B-X, I <sub>OUT</sub> = -200	SGM42507B-X Law = -200mA	+25°C		185		mΩ
			Full			360	
		SGM42507C-X, I <sub>OUT</sub> = -200mA	+25°C		210		
			Full			395	
Off-State Leakage Current	I <sub>OFF</sub>	V <sub>OUT</sub> = 0V or 7.5V	+25°C	-800		800	nA



# **ELECTRICAL CHARACTERISTICS (continued)**

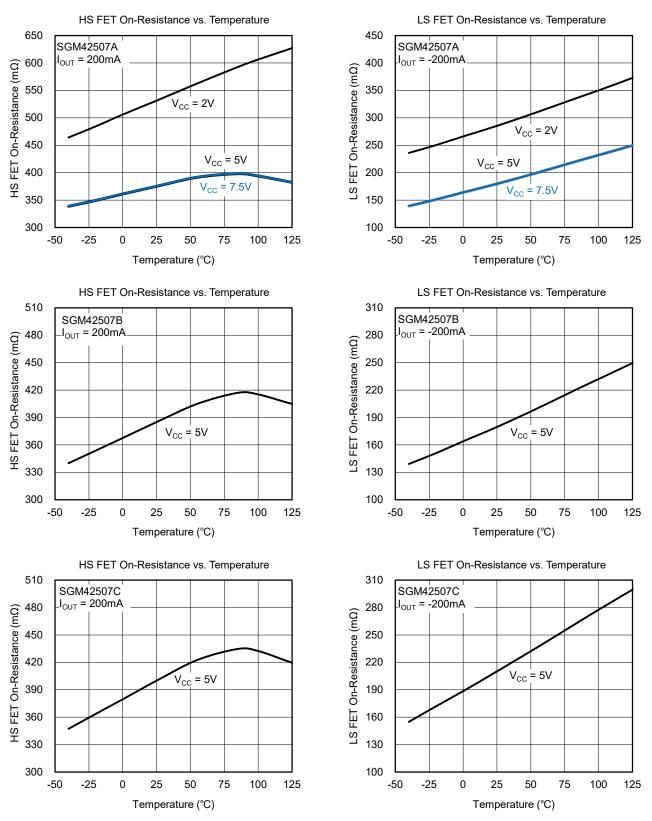
 $(T_A = +25^{\circ}C, V_{CC} = 5V, EN/FAULT pin connected to 5V through 500\Omega$  resistor, Full = -40°C to +125°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
MOTOR DRIVER							
Rise Time	t <sub>R</sub>	R <sub>L</sub> = 16Ω to GND, 10% to 90% V <sub>CC</sub>	+25℃		125		ns
Fall Time	t <sub>F</sub>	$R_L$ = 16Ω to V <sub>CC</sub> , 90% to 10% V <sub>CC</sub>	+25°C		155		ns
Propagation Delay INx to OUTx	t <sub>PROP</sub>		+25°C		1		μs
Dead Time <sup>(1)</sup>	t <sub>DEAD</sub>		+25°C		255		ns
PROTECTION CIRCUITS		·			•		
		SGM42507A-X	+25°C		1.5		A
Over-Current Protection Trip Level	I <sub>OCP</sub>	SGM42507B-X	+25°C		0.9		
		SGM42507C-X	+25°C		0.45		
PROTECTION CIRCUITS		·			•		
Thermal Shutdown Temperature	T <sub>TSD</sub>				165		°C
Thermal Shutdown Temperature Hysteresis	T <sub>HYS</sub>				30		°C
SLEEP MODE	•		•				
Enter Sleep Mode Time	t <sub>SLEEP</sub>		+25°C	60		105	ms
Wake Time	t <sub>WAKE</sub>	EN/FAULT inactive high to H-bridge on	+25℃			4.5	ms

NOTE: 1. Internal dead time. External implementation is not necessary.

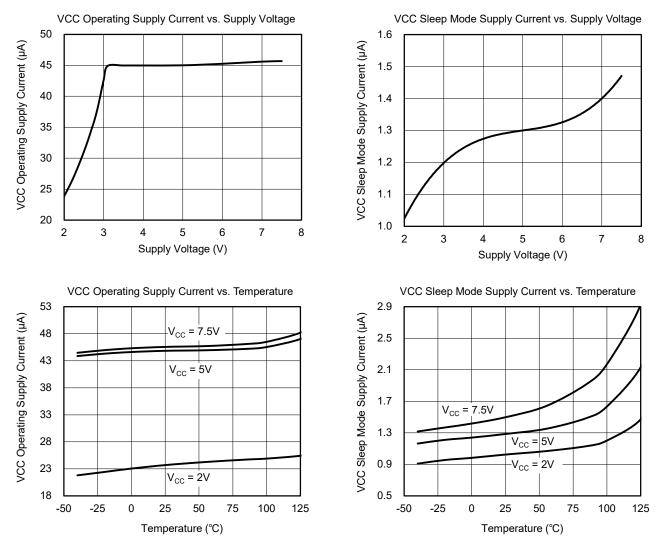


## **TYPICAL PERFORMANCE CHARACTERISTICS**



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# **TYPICAL PERFORMANCE CHARACTERISTICS (continued)**



## **DETAILED DESCRIPTION**

#### **H-Bridge Control and Sleep Mode**

The device has two push-pull stages that drive a bridge-tied load between those stages. When the stages are enabled, input PH selects driving direction into the load. When PH = 1, OUTA is H and OUTB is L; when PH = 0, OUTA is L and OUTB is H.

EN/FAULT is a dual function bi-directional input or output. When EN/FAULT is driven externally, if using EN/FAULT to alert stalling or other protections, the driving capability of external driver needs to be verified, to ensure that EN/FAULT has the sinking capability to pull down the driver. EN/FAULT can be tied to 1.9V ~ 5.5V through  $500\Omega$  resistor.

#### **EN/FAULT** as Output Port:

When any of over-current protection, under-voltage protection or over-temperature protection occurs, the device sinks current from EN/FAULT, pulling the pin down to alert the host.

EN/FAULT changes back to an input port, only after the device is released from a protection action.

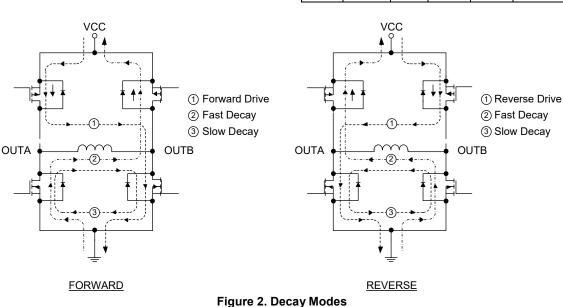
#### **EN/FAULT** as Input Port:

EN/FAULT = 1 enables driving load in the direction set by PH input, as shown in **Table 1 (a, b)**.

When EN/FAULT changes from 1 to 0, the state of PH is latched at this time. After the current direction of the load is consistent with the PH, the output stages will drive both OUTA and OUTB to ground, as shown in **Table 1 (c)**; if the duration of EN/FAULT = 0 is greater than  $t_{SLEEP}$ , the device will enter low power dissipation sleep mode, and keep both OUTA and OUTB to ground.

After EN/FAULT becomes 0, if PH changes even once at any time during EN/FAULT = 0, the output stages will immediately drive both OUTA and OUTB to highimpedance state, as shown in **Table 1 (d, e)**; if the duration of EN/FAULT = 0 is greater than  $t_{SLEEP}$ , the device will enter low power dissipation sleep mode, and keep both OUTA and OUTB to high-impedance state.

STATE	EN/ FAULT	PH	OUTA	OUTB	FUNCTION
(a)	1	1	Н	L	Forward
(b)	1	0	L	Н	Reverse
(c)	0	Х	L	L	Slow Decay/Brake
(d)	0	1→0	Z	Z	Fast Decay/Coast
(e)	0	0→1	Z	Z	Fast Decay/Coast



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## **DETAILED DESCRIPTION (continued)**

#### **PWM Motor Drivers**

The inputs can be used for PWM control of the motor speed and/or direction.

Loading PWM signal to EN/FAULT port, the output stages can realize single-side PWM output, in the direction set by PH, as shown in **Table 2** and **Figure 3**.

Loading PWM signal to PH port, the output stages can realize complementary PWM output in the direction set by PWM duty cycle, as shown in **Table 2** and **Figure 4**.

#### Table 2. PWM Control of Motor Speed

EN/FAULT	РН	OUTA, OUTB	FUNCTION	PWM MODE	
PWM <sup>(1)</sup>	н	OUTA = PWM, OUTB = GND	Forward PWM Control of Motor Speed	Single-side PWM Mode	
PWM <sup>(1)</sup>	L	OUTA = GND, OUTB = PWM	Reverse PWM Control of Motor Speed	Single-side PWM Mode	
н	PWM (D < 50%)	OUTA = -PWM, OUTB = +PWM	Reverse PWM Control of Motor Speed	Complementary PWM Mode	
н	PWM (D > 50%)	OUTA = +PWM, OUTB = -PWM	Forward PWM Control of Motor Speed	Complementary PWM Mode	

NOTE: 1. The duration of EN/FAULT = L must be less than  $t_{SLEEP}$ , in a PWM period. Otherwise the device may enter the low power dissipation sleep mode.

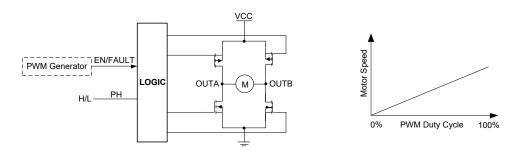


Figure 3. Loading PWM Signal to EN/FAULT Port

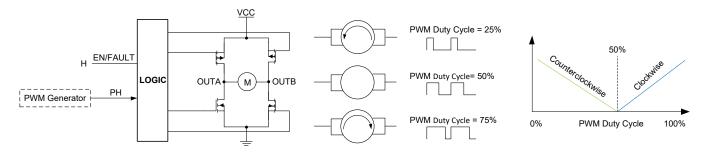


Figure 4. Loading PWM Signal to PH Port



## **DETAILED DESCRIPTION (continued)**

#### **Over-Current Protection**

When spinning starts or rotator stalls, driving current may increase sharply. The over-current protection is designed to alert the starting or stalling situation while providing necessary protection. The device drives both OUTA and OUTB to ground or power supply when the current is above the protection threshold for longer than the blanking time ( $40\mu$ s), and restores driving when the driving current falls below the threshold plus given hysteresis, while asserting an alert by pulling EN/FAULT low during the protection action. The average driving current is kept higher than the threshold current, so the torque or magnetic force is maintained during stalling or starting.

# Under-Voltage and Over-Temperature Protections

In any situations, including starting, stalling or functioning abnormally, if input voltage is lower than under-voltage threshold, the device drives both OUTA and OUTB to ground, or if die temperature rises higher than the over-temperature threshold, the device drives both OUTA and OUTB to high-impedance state to prevent the power system from collapsing or the die from thermal over-stress.

#### **Internal Pull-Down on Inputs**

Both PH and EN/FAULT have a continuous weak pull-down and a conditional strong pull-down. The

strong pull-down is active when input low is recognized and inactive when input high is recognized. This ensures a known and stable status for an input even when the input is floating, while keeping a low sinking current when the input is driven high.

#### **FMEA Fault Tolerance**

Any of two adjacent pin short does not cause damage to this device and its loading.

Table 3	. Adjacent	<b>Pin Short</b>	Effect
---------	------------	------------------	--------

SHORT PINS	EFFECT
VCC-PH	Equals to PH = 1. If EN/FAULT is high, OUTA to OUTB driving is selected, and all protections function normally.
PH-GND	Equals to PH = 0. If EN/FAULT is high, OUTB to OUTA driving is selected, and all protections function normally.
VCC-EN/FAULT	Equals to EN/FAULT = 1. EN/FAULT = 1 enables driving load in the direction set by PH, while all protections function normally.
EN/FAULT-GND	Equals to EN/FAULT = 0. The device will drive both OUTA and OUTB to ground/high-impedance state, or enter low power dissipation sleep mode.
OUTx-GND	The device will enter the over-current protection mode.
VCC-OUTx	The device will enter the over-current protection mode.
OUTA-OUTB	The device will enter the over-current protection mode.

## **REVISION HISTORY**

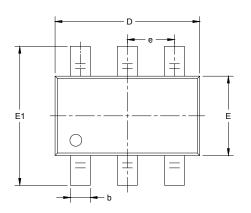
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

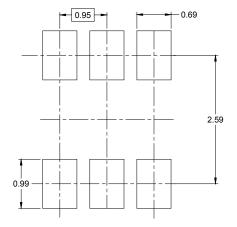
#### Changes from Original (NOVEMBER 2018) to REV.A

Changed from product preview to production data......All

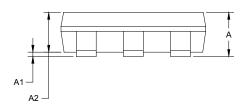
# PACKAGE OUTLINE DIMENSIONS

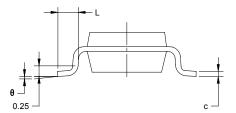
# **TSOT-23-6**





RECOMMENDED LAND PATTERN (Unit: mm)

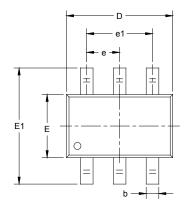


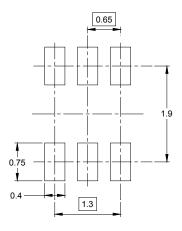


Symbol	-	nsions meters	Dimensions In Inches		
-	MIN	MAX	MIN	MAX	
А		1.000		0.043	
A1	0.000	0.100	0.000	0.004	
A2	0.700	0.900	0.028	0.039	
b	0.300	0.500	0.012	0.020	
с	0.080	0.200	0.003	0.008	
D	2.850	2.950	0.112	0.116	
E	1.550	1.650	0.061	0.065	
E1	2.650	2.950	0.104	0.116	
e	0.950	) BSC	0.037 BSC		
L	0.300	0.600	0.012	0.024	
θ	0°	8°	0°	8°	

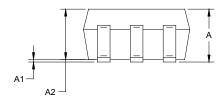
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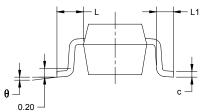
# SC70-6





RECOMMENDED LAND PATTERN (Unit: mm)



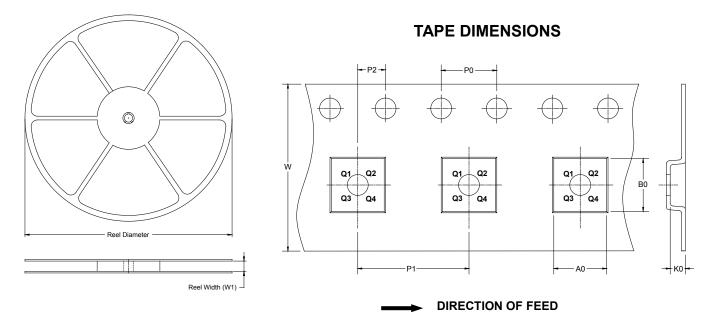


Symbol		nsions meters	Dimensions In Inches		
	MIN	MAX	MIN	MAX	
A	0.900	1.100	0.035	0.043	
A1	0.000	0.100	0.000	0.004	
A2	0.900	1.000	0.035	0.039	
b	0.150	0.350	0.006	0.014	
с	0.080	0.150	0.003	0.006	
D	2.000	2.200	0.079	0.087	
E	1.150	1.350	0.045	0.053	
E1	2.150	2.450	0.085	0.096	
е	0.65	TYP	0.026 TYP		
e1	1.300 BSC		0.051 BSC		
L	0.525 REF		0.021 REF		
L1	0.260	0.460	0.010	0.018	
θ	0°	8°	0°	8°	



# TAPE AND REEL INFORMATION

## **REEL DIMENSIONS**



NOTE: The picture is only for reference. Please make the object as the standard.

## KEY PARAMETER LIST OF TAPE AND REEL

Package Type	Reel Diameter	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	P1 (mm)	P2 (mm)	W (mm)	Pin1 Quadrant
SC70-6	7″	9.5	2.40	2.50	1.20	4.0	4.0	2.0	8.0	Q3
TSOT-23-6	7"	9.5	3.20	3.10	1.10	4.0	4.0	2.0	8.0	Q3

## **CARTON BOX DIMENSIONS**



NOTE: The picture is only for reference. Please make the object as the standard.

## **KEY PARAMETER LIST OF CARTON BOX**

Reel Type	Length (mm)	Width (mm)	Height (mm)	Pizza/Carton	
7" (Option)	368	227	224	8	
7"	442	410	224	18	00002

